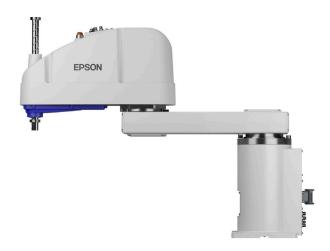


Epson[®] GX20C SCARA Robot



Epson GX—taking SCARA performance to the next level.

Ultra high performance and flexibility — high throughput with heavy payloads and multiple arm configurations to accomplish the most demanding assembly needs

Fast cycle times — high acceleration, smooth motion and fast settling times help maximize throughput with proprietary GYROPLUS™ vibration reduction system, plus no ringing or overshoot¹

Ultimate ease of use — intuitive and feature-packed Epson RC+® development software helps create powerful solutions with a simple user interface, integrated debugger and advanced 3D simulator

Designed for reliability — innovative, compact design handles heavy workloads at fast speeds and high precision within a small footprint

Low total cost of ownership — includes features that help reduce support and installation costs: batteryless encoders, a built-in Ethernet cable, Epson RC+ software and a rich suite of safety features

Accelerate the development of workcell applications — fully integrated, optional solutions include vision guidance, parts feeding, force guidance, conveyor tracking and fieldbus; Epson RC+ Solutions Platform allows for seamless expansion of third-party solutions, benefiting developers and end users

Increase user interaction without sacrificing productivity — SafeSense $^{\text{\tiny M}}$ technology's standard and advanced safety features, with a

proper risk assessment, help allow for increased productivity and worker protection while potentially minimizing machine footprint due to the reduction of physical barriers

Minimize the workcell space requirement with an optimized robot footprint — multiple mount and cable exit options; 850 mm or 1,000 mm reach available

Built for demanding environments — Standard, Cleanroom (ISO 3)² and ESD, and Protected IP65 models available



Epson® GX20C SCARA Robot

Model Name		GX20C SCARA Robot								
Model Number			GX20-C85x			GX20-CA0x				
Mounting Type		Tabletop	Ceiling	Wall	Tabletop	Ceiling	Wall			
Arm Length	Joint #1 Plus Joint #2	Tablotop	850 mm	Train	Tublotop	1,000 mm	Trus.			
7 <u>2</u> 0g	Joints #1 - #2	±0.025 mm								
Repeatability	Joint #3	±0.010 mm								
	Joint #4	±0.005 deq								
	Rated	±0.003 deg								
Payload	Max.	20 kg								
Standard Cycle Time ³		0.37 sec 0.42 sec								
otaniaa a oyono iiiio	Joint #1	±152 deg		7 deg			±107 deg			
	Joint #2 Std			9		±152.5 deg				
Max. Motion Range	Joint #2 Clean & Protected	±152.5 deg	±13	0 deg	Z: 0~-360 mm ± 152.5 deg Z: -360~-390 mm ± 151 deg					
	Joint #3 Std	180 mm/420 mm								
	Joint #3 Clean	150 mm/390 mm								
	Joint #4	±360 deg								
Joint #4 Allowable	Rated	0.05 kg·m²								
Moment of Inertia⁴	Max.	0.45 kg·m²								
Joint #3 Downforce		250 N								
User Electric Lines		15-pin (D-sub), 9-pin (D-sub)								
User Pneumatic Lines		ø4 mm x2, ø6 mm x2								
Brakes		Joint #3 and Joint #4								
Power		AC 200 V - 240 V (single phase)								
Power Consumption		2.5 kVa								
Power Cable Length		3 m/5 m/10 m (straight and angled cable end options)								
Weight (Cables Not Included)		49 kg, 108 lb 53 kg, 117 lb			50 k	g, 110 lb	55 kg, 121 lb			
Applicable Controller		RC800A								
Installation Environment		Standard/Cleanroom ISO3° & ESD/Protected								
Safety Standards		TUV Certified to meet ISO 10218-1, UL 1740, CSA Z434, ISO 13849								
What's Included		GX20C robot and RC800A controller, E-Stop unit with cable and connector, cable with flying leads for controller E-stop/Safety connection, connector set (I/O, hand I/O and safety circuit connectors)								
Options		Vicion	Guido	Available						
		Vision Guide		Available						
		IntelliFlex™ Feeders		Available						
		Force Guide		Available						
		Conveyor Tracking Epson RC+ API 8.0		R19NZ901JK						
		GUI Builder 8.0		R19NZ901JQ						
		Fieldbus Master		Available						
		Fieldbus Slave (Ethernet/IP, EtherCAT®, PROFINET, PROFIBUS, CC-Link)		Available						
		External Control Point (ECP) 8.0		R19NZ901JL						
		Teach Pendant		Available						
		Epson OPC UA for Robotics		R19NZ901JZ						
		Arm Length Calibration		R19NZ901JW						
			idard and Long Z)	Available						
		Dollows Mr (Stal	ida. a unu Long L)	Available						

Support

Customer Service (562) 290-5920 service@robots.epson.com Applications Support (562) 290-5930 applications@robots.epson.com

Sales Inquiries (562) 290-5997 info@robots.epson.com

1 When operated within specifications. 2 Complies with ISO Class 3 (ISO 14644-1) and FED-STD-209D Class 1
cleanroom standards. 3 Cycle time based on round-trip arch motion (300 mm horizontal, 25 mm vertical) with 2 kg payload for
tabletop model boost mode (path coordinates optimized for maximum speed). 4 When payload center of gravity is aligned with
Joint #4; if not aligned with Joint #4, set parameters using INERTIA command.

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Epson America, Inc. 3131 Katella Ave., Los Alamitos, CA 90720

Epson Canada Limited

185 Renfrew Drive, Markham, Ontario L3R 6G3

www.epson.com www.epson.ca

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Contact:									