EPSON[®]

Epson[®] GX4C SCARA Robot



Epson GX—taking SCARA performance to the next level.

Ultra high performance and flexibility — high throughput with maxrated payloads and multiple arm configurations to accomplish the most demanding assembly needs

Fast cycle times — high acceleration, smooth motion and fast settling times help maximize throughput with proprietary GYROPLUS[™] vibration reduction system, plus no ringing or overshoot¹

Ultimate ease of use — intuitive and feature-packed Epson RC+[®] development software helps create powerful solutions with a simple user interface, integrated debugger and advanced 3D simulator

Designed for reliability — innovative, compact design handles maxrated workloads at fast speeds and high precision within a small footprint

Low total cost of ownership — includes features that help reduce support and installation costs: batteryless encoders, a built-in Ethernet cable, Epson RC+ software and a rich suite of safety features

Accelerate the development of workcell applications — fully integrated, optional solutions include vision guidance, parts feeding, force guidance, conveyor tracking and fieldbus; Epson RC+ Solutions Platform allows for seamless expansion of third-party solutions, benefiting developers and end users

Increase user interaction without sacrificing productivity — SafeSense[™] technology's standard and advanced safety features, with a proper risk assessment, help allow for increased productivity and worker protection while potentially minimizing machine footprint due to the reduction of physical barriers

Minimize the workcell space requirement with an optimized robot footprint — multiple mount and cable exit options; 250 mm, 300 mm or 350 mm reach available; unique curved arm (350 mm) option maximizes work envelope

Built for demanding environments — Standard, Cleanroom (ISO 3)² and ESD, and standalone ESD models available

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Model Name					GX4C SCARA Robot			
Model Number			GX4-C251x	GX4-	C301x	GX4-C	351x	
Mounting Type			Tabletop	Tabletop	Multiple	Tabletop	Multiple	
Arm Length			250 mm) mm	350 mm		
	Joints #1 - #2		±0.008 mm ±0.001 mm					
Repeatability Joint #3 Joint #4 Payload Rated Max. Standard Cycle Time ³		±0.01 mm						
		±0.005 deg						
		2 kg						
		4 kg						
		0.33 sec 0.34 sec 0.35 sec						
		Joint #1	±140 deg	±140 deg	±115 deg	±140 deg	±120 deg	
	Straight	Joint #2 Std	±141 deg	±142 deg	±110 d0g	±140 dog	120 009	
		Joint #2 Clean	±137 deg	±141 deg	- ±135 deg	±142 deg		
	Curved	Joint #1 Right Hand	-110 ~ 165 deg					
Max. Motion Range		Joint #1 Left Hand	-165 ~ 110 c					
		Joint #2 Right Hand Std & ESD				-120 ~ 165 deg		
		Joint #2 Right Hand Clean				-120 ~ 160 deg		
		Joint #2 Left Hand Std & ESD	-165 ~ 120 deg					
		Joint #2 Left Hand Clean	-160 ~ 120 deg				-	
		Joint #2 Left Hand Clean			150 mm	-100 ~ 120 ueg		
	All Models		150 mm					
		Joint #3 Clean	120 mm					
		Joint #4	±360 deg					
Joint #4 Allowable Moment of Inertia⁴		Rated	0.005 kg·m²					
		0.05 kg·m²						
Joint #3 Downforce		150 N						
User Electric Lines			15	5-pin (D-sub), 8-pin (RJ45 Cat	56)			
User Pneumatic Lines			Ø4 mm x1, Ø6 mm x2					
Brakes			Z axis only					
Power		AC 200 V – 240 V (single phase)						
Power Consumption					1.2 kVa			
Power Cable Length (Cables Ordered Separately)				0 m (straight and angled cable)				
Bottom Cable Exit Option (Tabletop Only)		Available	Available	-	Available	-		
Weight (Cables Not Included)		15 kg, 33 lb	15 kg, 33 lb	17 kg, 38 lb	16 kg, 35 lb	17 kg, 38 lb		
Applicable Controller			RC800A					
Installation Environment			Standard/ESD/Cleanroom ISO Class 3 ² with ESD					
Safety Standards			TUV Certified to meet ISO 10218-1, UL 1740, CSA Z434, ISO 13849					
What's Included			GX4C robot and RC800A controller, E-Stop unit with cable and connector, cable with flying leads for controller					
				E-stop/Safety connection,	connector set (I/O, hand I/O and	d safety circuit connectors)		
Options								
			Vision Guide Available					
			IntelliFlex [™] Feeders		Available			
			Force Guide		Available			
					Available			
			Epson RC+ API 8.0		R19NZ901JK			
			GUI Builder 8.0		R19NZ901JQ			
					Available			
			Fieldbus Slave (Ethernet/IP, EtherCAT®, PROFINET, PROFIBUS, CC-Link)		Available			
					R19NZ901JL			
			Teach Pendant Available		Available			
			Epson OPC UA for Robotics R19NZ901JZ					
			Arm Length Calibration R19NZ901JW					
			Bellows Kit (Standard and Long Z) Available					
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1 When operated within specifications. | 2 Complies with ISO Class 3 (ISO 14644-1) and FED-STD-209D Class 1 cleanroom standards. | 3 Cycle time based on round-trip arch motion (300 mm horizontal, 25 mm vertical) with 2 kg payload for tabletop model boost mode (path coordinates optimized for maximum speed). | 4 When payload center of gravity is aligned with Joint #4; if not aligned with Joint #4, set parameters using INERTIA command.

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